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ON SOME RESONANT BOUNDARY VALUE PROBLEM ON AN INFINITE INTERVAL

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ABSTRACT. The existence of at least one solution to a nonlinear second order differential equation on the half-line with the boundary conditions x'(0) = 0 and with the first derivative vanishing at infinity is proved.

1. Introduction

In the paper the following asymptotic boundary value problem

(1.1)
$$x'' = f(t, x, x'), \quad x'(0) = 0, \quad \lim_{t \to \infty} x'(t) = 0,$$

where $f: \mathbb{R}_+ \times \mathbb{R}^k \times \mathbb{R}^k \to \mathbb{R}^k$ is continuous and satisfies the appropriate growth conditions, is studied. Observe that the corresponding homogeneous linear problem, i.e.

$$x'' = 0, \quad x'(0) = 0, \quad \lim_{t \to \infty} x'(t) = 0,$$

has nontrivial constant solutions; hence we deal with a resonant situation.

The problem (1.1) has been already studied in [13]. In that paper, we have obtained the existence result in a completely different way than by using standard methods for resonant problems (by standard methods we mean methods considered, for instance, in the following papers: [1]–[4], [7], [10]–[12]). The

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method used in [13] enabled us to get existence under weak assumptions: a linear growth condition and a sign condition for the nonlinear term f. Similar assumptions appear also for other boundary value problems.

2. Preliminaries

First, we shall introduce notation and terminology.

By a space we mean a metric space. Given a space X with a metric d, a set $A \subset X$ and $\varepsilon > 0$, $B(A, \varepsilon) := \{x \in X \mid d_A(x) := \inf_{a \in A} d(x, a) < \varepsilon\}$ denotes the open ε -neighbourhood of A. Recall that a space X is an absolute neighbourhood retract (we write $X \in ANR$) if, given a space Y and a homeomorphic embedding $i: X \to Y$ of X onto a closed subset $i(X) \subset Y$, i(X) is a neighbourhood retract of Y, i.e. there is an open neighbourhood U of i(X) in Y and a retraction $r: U \to i(X)$ (a map $r: U \to i(X)$ is a retraction provided that r(y) = y for $y \in i(X)$).

We shall say that a nonempty space X is contractible provided there exist $x_0 \in X$ and a homotopy $h: X \times [0, 1] \to X$ such that h(x, 0) = x and $h(x, 1) = x_0$ for every $x \in X$.

A compact (nonempty) space X is an R_{δ} -set (we write $X \in R_{\delta}$) if there is a decreasing sequence X_n of compact contractible spaces such that $X = \bigcap_{n>1} X_n$.

Let X, Y be spaces. A set-valued map $\Phi: X \to Y$ is upper semicontinuous (written u.s.c.) if, given an open $V \subset Y$, the set $\{x \in X \mid \Phi(x) \subset V\}$ is open. We say that $\Phi: X \to Y$ is an R_{δ} -map if it is u.s.c. and, for each $x \in X$, $\Phi(x) \in R_{\delta}$.

By a decomposable map we mean a pair (D, F) consisting of a set-valued map $F: X \multimap Y$ and a diagram $D: X \xrightarrow{\Phi} Z \xrightarrow{\varphi} Y$, where $Z \in ANR$, $\Phi: X \multimap Z$ is an R_{δ} -map, and $\varphi: Z \to Y$ a single-valued continuous map, such that $F = \varphi \circ \Phi$.

A superposition of a set-valued map with compact values and a continuous function is an u.s.c. map, so any decomposable map is u.s.c.

We say the two decomposable maps (D_0, F_0) , (D_1, F_1) where $D_k: X \xrightarrow{\Phi_k} Z_k \xrightarrow{\varphi_k} Y$, k = 0, 1 are homotopic (we write $(D_0, F_0) \simeq (D_1, F_1)$) if there is a decomposable map (\check{D}, \check{F}) with $\check{D}: X \times [0, 1] \xrightarrow{\check{\Phi}} Z \xrightarrow{\check{\varphi}} Y$ and maps $j_k: Z_k \to Z$, k = 0, 1 such that the diagram



where $i_k(x) = (x, k)$ for $x \in X$, k = 0, 1, is commutative.

THEOREM 2.1 ([8, p. 1797]). If a decomposable map $(D, F): X \multimap X$, where X is a compact ANR and is homotopic to identity id_X , i.e. there is a decomposable map $(D', F'): X \multimap X$ such that $(D, F) \simeq (D', F')$ and F'(x) = x for $x \in X$, then

$$\Lambda(D, F) = \lambda(\mathrm{id}_X) = \chi(X).$$

Hence, if $\chi(X) \neq 0$, then $\operatorname{Fix}(F) \neq \emptyset$.

The following simple corollary will be of crucial importance.

COROLLARY 2.2. Let Q be a compact polyhedron with nontrivial Euler characteristic $\chi(Q) \neq 0$. If a decomposable map $(D, F): Q \multimap Q$ is homotopic to identity, then $\operatorname{Fix}(F) \neq \emptyset$.

Now, we shall present a result about the topological structure of the set of solutions of some nonlinear functional equation.

THEOREM 2.3 ([6, p. 159]). Let X be a space, $(E, \|\cdot\|)$ a Banach space and h: $X \to E$ a proper map, i.e. h is continuous and for every compact $K \subset E$ the set $h^{-1}(K)$ is compact. Assume further that for each $\varepsilon > 0$ a proper map $h_{\varepsilon}: X \to E$ is given and the following two conditions are satisfied:

- (a) $||h_{\varepsilon}(x) h(x)|| < \varepsilon$, for every $x \in X$;
- (b) for any $\varepsilon > 0$ and $u \in E$ such that $||u|| \le \varepsilon$, the equation $h_{\varepsilon}(x) = u$ has exactly one solution.

Then the set $S = h^{-1}(0)$ is R_{δ} .

Denote by $BC(\mathbb{R}_+, \mathbb{R}^k)$ (we write BC) the Banach space of continuous and bounded functions with supremum norm and by $BCL(\mathbb{R}_+, \mathbb{R}^k)$ (we write BCL) its closed subspace of continuous and bounded functions which have finite limits at $+\infty$.

The following theorem gives a sufficient condition for compactness in the space BC and, by the definition, in the space BCL as well.

THEOREM 2.4 ([9]). If $B \subset BC$ satisfies following conditions:

- (a) there exists L > 0, that for every $x \in B$ and $t \in [0, \infty)$ we have $|x(t)| \leq L$,
- (b) for each $t_0 \ge 0$, the family B is equicontinuous at t_0 ,
- (c) for any $\varepsilon > 0$ there exist T > 0 and $\delta > 0$ such that if $|x(T) y(T)| \le \delta$, then $|x(t) - y(t)| \le \varepsilon$ for $t \ge T$ and all $x, y \in B$.

Then B is relatively compact in BC.

3. The main result

Let us consider an asymptotic BVP

(3.1)
$$x'' = f(t, x, x'), \quad x'(0) = 0, \quad \lim_{t \to \infty} x'(t) = 0,$$

where $f: \mathbb{R}_+ \times \mathbb{R}^k \times \mathbb{R}^k \to \mathbb{R}^k$ is continuous.

The following assumptions will be needed throughout the paper:

- (i) $|f(t,x,y)| \le a(t)|y| + b(t)$, where $\int_0^\infty a(s) \, ds < \infty$, $\int_0^\infty b(s) \, ds < \infty$;
- (ii) there exists M > 0 such that $x_i f_i(t, x, y) > 0$ for $t \ge 0, y \in \mathbb{R}^k, x \in \mathbb{R}^k$ and $|x_i| \ge M, i = 1, \dots, k$.

DEFINITION 3.1. A function $x: \mathbb{R}_+ \to \mathbb{R}^k$ is called a solution of (3.1) if the following holds:

- (a) $x \in C^2(\mathbb{R}_+, \mathbb{R}^k);$
- (b) x''(t) = f(t, x(t), x'(t)) for every $t \in \mathbb{R}_+$;
- (c) x'(0) = 0, $\lim_{t \to \infty} x'(t) = 0$.

Now, we can formulate our main result.

THEOREM 3.2. Under assumptions (i) and (ii), problem (3.1) has at least one solution.

The proof will be divided into a sequence of lemmas. Given $c \in \mathbb{R}^k$ and $x \in \text{BCL}$ let

$$A(c,x)(t) = \int_0^t f\left(s, c + \int_0^s x(u) \, du, x(s)\right) ds, \quad t \ge 0.$$

It is clear that $A(c, x): [0, \infty) \to \mathbb{R}^k$ is continuous. For $t \ge 0$,

$$|A(c,x)(t)| \le \int_0^t (a(s)|y_c(s)| + b(s)) \, ds \le M_1 ||x||_{\mathrm{BC}} + M_2,$$

where

$$M_1 := \int_0^\infty a(s) \, ds, \quad M_2 := \int_0^\infty b(s) \, ds.$$

Hence

(3.2)
$$||A(c,x)(t)||_{BC} \le M_1 ||x||_{BC} + M_2.$$

Therefore $A(c, x) \in BC$.

Moreover, observe that the function $[0, \infty) \ni t \mapsto f(t, c + \int_0^t y_c(u) \, du, y_c(t))$ is integrable. Hence, in particular, $\lim_{t\to\infty} A(c, x)(t)$ exists, i.e. $A(c, x) \in \text{BCL}$. It follows that the operator $A: \mathbb{R}^k \times \text{BCL} \to \text{BCL}$ is well-defined.

LEMMA 3.3. Under assumption (i) the operator $A: \mathbb{R}^k \times BCL \to BCL$ is completely continuous.

PROOF. The continuity of A is an easy consequence of the Lebesque Dominated Convergence Theorem. It order to prove the complete continuity let us consider the set $B := \{y = A(c, x) \mid c \in \mathbb{R}^k, \|x\| \le R\}$, where R > 0. We shall see that B is relatively compact in BCL. To this reason we use Theorem 2.4.

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First observe that B is bonded (see (3.2)): for any $y \in B$,

$$||y||_{\mathrm{BC}} \leq M_1 R + M_2.$$

Hence the condition (a) of the Theorem 2.4 holds true.

We shall now show that the family B is equicontinuos, i.e. given $t_0 \ge 0$ and $\varepsilon > 0$, there is $\delta > 0$ such that if $t \ge 0$ and $|t - t_0| < \delta$, then $|y(t) - y(t_0)| < \varepsilon$ for any $c \in \mathbb{R}^k$ and $y \in B$. Let us choose an arbitrary $\varepsilon > 0$. By (i), there exist $\delta_1, \delta_2 > 0$ such that

$$\begin{aligned} &\text{if} \quad |t - t_0| < \delta_1, \quad \text{then} \quad \int_{\min\{t_0, t\}}^{\max\{t_0, t\}} a(s) \, ds < \frac{\varepsilon}{2R}, \\ &\text{if} \quad |t - t_0| < \delta_2, \quad \text{then} \quad \int_{\min\{t_0, t\}}^{\max\{t_0, t\}} b(s) \, ds < \frac{\varepsilon}{2}. \end{aligned}$$

Let $\delta = \min{\{\delta_1, \delta_2\}}$. Then, for $|t - t_0| < \delta$, we get

$$\begin{aligned} |y(t) - y(t_0)| &\leq \int_{\min\{t_0, t\}}^{\max\{t_0, t\}} \left| f(s, c + \int_0^s x(u) \, du, x(s)) \right| ds \\ &\leq R \int_{\min\{t_0, t\}}^{\max\{t_0, t\}} a(s) \, ds + \int_{\min\{t_0, t\}}^{\max\{t_0, t\}} b(s) \, ds < R \frac{\varepsilon}{2R} + \frac{\varepsilon}{2} = \varepsilon. \end{aligned}$$

It remains to prove condition (c) of Theorem 2.4, i.e. we shall show that given $\varepsilon > 0$, there are T > 0 and $\delta > 0$ such that for any $y, z \in B$ if $|y(T) - z(T)| < \delta$, then $|y(t) - z(t)| < \varepsilon$ for any $t \ge T$. There is T > 0 such that

$$\int_{T}^{\infty} a(s) \, ds < \frac{\varepsilon}{6R}, \quad \int_{T}^{\infty} b(s) \, ds < \frac{\varepsilon}{6}.$$

Let $\delta := \varepsilon/3$. If $|y(T) - z(T)| \le \delta$, then for $t \ge T$ we get

$$\begin{aligned} |y(t) - z(t)| &\leq |y(T) - z(T)| + 2R \int_T^\infty a(s) \, ds + 2 \int_T^\infty b(s) \, ds \\ &\leq \frac{\varepsilon}{3} + 2R \frac{\varepsilon}{6R} + 2\frac{\varepsilon}{6} = \varepsilon, \end{aligned}$$

and the proof is complete.

Given $c \in \mathbb{R}^k$, let $x \in BCL$ and $x = \lambda A(c, x)$ for some $\lambda \in [0, 1]$. Then

$$x(t) = \lambda \int_0^t f\left(s, c + \int_0^s x(u) \, du, x(s)\right) ds.$$

The Gronwall inequality implies that

$$(3.3) |x(t)| \le M_2 e^{M_1}$$

Therefore, the Leray–Schauder Alternative implies that for each $c \in \mathbb{R}^k$ the set $\operatorname{Fix}(A(c, \cdot))$ of fixed points of $A(c, \cdot)$: BCL \to BCL is nonempty.

LEMMA 3.4. Let assumption (i) hold and let $\Phi: \mathbb{R}^k \multimap BCL$ be given by $\Phi(c) := Fix(A(c, \cdot))$. The set-valued map Φ is upper semicontinuous with compact values.

PROOF. The set-valued map Φ is upper semicontinuous with compact values if given a sequence (c_n) in \mathbb{R}^k , $c_n \to c_0$ and $(x_n) \in \Phi(c_n)$, (x_n) has a converging subsequence to some $x_0 \in \Phi(x_0)$. Taking any sequence (c_n) , $c_n \to c_0$ and $(x_n) \in \Phi(c_n)$ we have

$$(3.4) x_n = A(c_n, x_n)$$

By (3.3), we get that the fixed points of $A(c, \cdot)$ are equibounded for any c. Hence both sequences (x_n) and (c_n) are bounded. Lemma 3.3 yields that the operator A is completely continuous. Then, by (3.4), (x_n) is relatively compact. Hence, passing to a subsequence if necessary, we may assume that $x_n \to x_0$ in BCL. The continuity of A implies that $x_0 = A(c_0, x_0)$. Hence, $x_0 \in \Phi(c_0)$ and the proof is complete.

LEMMA 3.5. If assumption (i) holds, then Φ is an R_{δ} -map.

PROOF. Since the map Φ is u.s.c., it remains to show that for any $c \in \mathbb{R}^k$ the set $\Phi(c)$ is R_{δ} . Let $X = \{x \in \text{BCL} \mid ||x|| \leq L\}$, where $L := M_2 e^{M_1}$ is taken from (3.3). We will show that if $A(c, \cdot): X \to \text{BCL}$ is a compact map (it is easy to see that A_c is compact) and $h: X \to \text{BCL}$ is a compact vector field associated with $A(c, \cdot)$, i.e. h(x) = x - A(c, x), then there exists a sequence $h_n: X \to \text{BCL}$ of continuous proper mappings satisfying conditions (a) and (b) of Theorem 2.3 with respect to h.

First, notice that A(c, x) = 0 for every $x \in X$. Moreover, for every $T \in (0, \infty)$ and for every $x, y \in BCL$, if x(t) = y(t) for each $t \in [0, T]$, then A(c, x)(t) = A(c, y)(t) for each $t \in [0, T]$.

For the proof it is sufficient to define a sequence $A^n(c, \cdot): X \to \text{BCL}$ of compact maps such that $A(c, x) = \lim_{n \to \infty} A^n(c, x)$ uniformly in X and show that $h_n(x) = x - A^n(c, x)$ is a one-to-one map. To do this we define auxiliary mappings $r_n: \mathbb{R}_+ \to \mathbb{R}_+$ by

$$r_n(t) := \begin{cases} 0 & \text{for } t \in [0, 1/n], \\ t - 1/n & \text{for } t \in (1/n, \infty) \end{cases}$$

Now we are able to define the sequence $(A^n(c, \cdot))$ as follows

(3.5)
$$A^n(c,x) = A(c,x)(r_n(t)), \quad \text{for } x \in X, \ n \in \mathbb{N}.$$

It is easy to see that A_c^n are continuous and compact. Since $|r_n(t) - t| \leq 1/n$, we deduce from the compactness of $A(c, \cdot)$ and (3.5) that $A^n(c, x) \to A(c, x)$ uniformly in X.

Now, we shall prove that h_n is a one-to-one map. Assume that fore some $x, y \in X$ we have $h_n(x) = h_n(y)$. This implies that

$$x - y = A^n(c, x) - A^n(c, y).$$

If $t \in [0, 1/n]$, then we have

$$x(t) - y(t) = A(c, x)(r_n(t)) - A(c, y)(r_n(t)) = A(c, x)(0) - A(c, y)(0) = 0.$$

Thus, we obtain x(t) = y(t) for every $t \in [0, 1/n]$.

If $t \in [1/n, 2/n]$, then we have that $0 < r_n(t) \le 1/n$. Hence, by the property of operator A(c, ...) mentioned above, we get x(t) = y(t) for $t \in [0, 2/n]$. Finally, by repeating the procedure infinitely many times we infer that x(t) = y(t) for every $t \in [0, \infty)$. Therefore h_n is a one-to-one map. Hence the assumptions of Theorem 2.3 hold and $h^{-1}(0) = \operatorname{Fix} A(c, \cdot)$ is an R_{δ} -set. \Box

REMARK 3.6. For a different treatment of Lemma 3.5, see [5].

Let $\varphi: \operatorname{BCL} \to \mathbb{R}^k$ be given by $\varphi(y) = \lim_{t \to \infty} y(t)$. It is easily seen that φ is continuous. Hence the map $g = \varphi \circ \Phi$ is decomposable with a decomposition

$$\mathbb{R}^k \xrightarrow{\Phi} \mathrm{BCL} \xrightarrow{\varphi} \mathbb{R}^k.$$

If, for some $c \in \mathbb{R}^k$, $0 \in g(c)$, then there is $y \in \Phi(c)$ (in other words $y'(t) = f(t, c + \int_0^t y(s) \, ds, y(t))$) such that $0 = \lim_{t \to \infty} y(t)$. Putting $x(t) := c + \int_0^t y(s) \, ds$, we see that

$$x''(t) = f(t, x(t), x'(t)), \quad x'(0) = 0 = \lim_{t \to \infty} x'(t),$$

i.e. x is a solution to the initial equation (3.1).

Now, set $\widehat{M} := M + 1$, where M is as in (ii).

LEMMA 3.7. Let
$$Q := [-\widehat{M}, \widehat{M}]^k$$
. There is $\widetilde{c} \in Q$ such that $0 \in g(\widetilde{c})$.

PROOF. Let $c_i = \widehat{M}$ and $y \in \Phi(c)$. First, we shall show that $y_i(t) \ge 0$ for $t \ge 0$. We have $y_i(0) = 0$. Assume that for some t we have $y_i(t) < 0$. Then there exists $t_* := \inf\{t \mid y_i(t) < 0\}$ such that, $y_i(t_*) = 0$ and $y_i(t) \ge 0$ for $t < t_*$. Since $y_i(t)$ is continuous there exists $t_1 > t_*$ such that $\int_{t_*}^{t_1} |y_i(t)| dt \le 1$. Hence, we get

$$x_i(t) = c_i + \int_{t_*}^t y_i(s) \, ds \ge M + 1 + \int_{t_*}^t y_i(s) \, ds \ge M \quad \text{for } t \in [t_*, t_1].$$

Now, by condition (ii) we get $x_i(t)f_i(t, x(t), y(t)) = x_i(t)y'_i(t) > 0$. Hence $y'_i(t) > 0$ for $t \in [t_*, t_1]$. It means that $y_i(t)$ is increasing on $[t_*, t_1]$. Since $y_i(t_*) = 0$, we get a contradiction. Hence $y_i(t) \ge 0$ for $t \ge 0$.

Moreover, by the above arguments, $\lim_{t\to\infty} y_i(t) > 0$.

Let $d = (d_1, \ldots, d_k) \in \mathbb{R}^k$. By the definition of g, for $i = 1, \ldots, k$, we get

(3.6) if
$$d \in g(c_1, \ldots, c_{i-1}, \widehat{M}, c_{i+1}, \ldots, c_k)$$
, then $d_i > 0$.

We can proceed analogously to prove that, for every i = 1, ..., k,

(3.7) if
$$d \in g(c_1, \ldots, c_{i-1}, -\widehat{M}, c_{i+1}, \ldots, c_k)$$
, then $d_i < 0$

Let $g_i = P_i g$ for i = 1, ..., k, where $P_i: \mathbb{R}^k \to \mathbb{R}$ is the projection onto the *i*-th axis. By (3.6) and (3.7), for i = 1, ..., k, we have

$$g_i(c_1,\ldots,c_{i-1},\widehat{M},c_{i+1},\ldots,c_k) \subset (0,\infty),$$

$$g_i(c_1,\ldots,c_{i-1},-\widehat{M},c_{i+1},\ldots,c_k) \subset (-\infty,0).$$

It is easy to see that g_i is u.s.c. map. By (3.6) and the fact that g_i is u.s.c. there exists $\gamma_i > 0$ such that for any $c \in Q$, where $c_i \in (\widehat{M} - \gamma_i, \widehat{M}]$, we get $g_i(c) \subset (0, \infty)$, for every $i = 1, \ldots, k$. Similarly, by (3.7) and the fact that g_i is u.s.c. there exists $\beta_i > 0$ such that for any $c \in Q$, where $c_i \in [-\widehat{M}, -\widehat{M} + \beta_i)$, we have $g_i(c) \subset (-\infty, 0)$, for every $i = 1, \ldots, k$.

The image of g is compact, hence $\hat{g} := \sup\{|d| \mid d \in g_i(c), c \in Q, i = 1, \ldots, k\} < \infty$.

Let $\delta := \min \left\{ \beta_1, \ldots, \beta_k, \gamma_1, \ldots, \gamma_k, \widehat{M} \right\}$ and set $\varepsilon := \delta/\widehat{g}$. Considering the set-valued mapping given by $F_i(c) = c_i - \varepsilon g_i(c)$ we get the following inequality

 $-\widehat{M} \leq c_i - \varepsilon y \leq \widehat{M}$, for any $c_i \in [-\widehat{M}, \widehat{M}]$ and $y \in g_i(c)$.

Now, let us consider the multi-valued mapping $F(c) = c - \varepsilon g(c)$, where $c \in Q$. By the above, we get that F maps the hypercube Q into itself.

Let us define a pair (D,F) consisting of a set-valued map $F\colon\!Q\multimap Q$ and the diagram

$$D: Q \xrightarrow{\Phi_0} \mathrm{BCL} \xrightarrow{\varphi} Q,$$

where $F = \varphi \circ \Phi_0$ and $\Phi_0(c) := \{ x \in \text{BCL} \mid x(t) = c - \varepsilon y(t), t \in \mathbb{R}_+, y \in \Phi(c) \}.$

Notice, that BCL, as a Banach space, is ANR. Moreover, Φ_0 is an R_{δ} -map. Hence (D, F) is a decomposable map.

Now, to apply Corollary 2.2, it is sufficient to show that the decomposable map (D, F) is homotopic to the identity id_Q , which means that there exists a decomposable map $(D', F'): Q \multimap Q$ such that $(D, F) \simeq (D', F')$ and F'(c) = c for $c \in Q$.

Let $D': Q \xrightarrow{\Phi_1} BCL \xrightarrow{\varphi} Q$, where $\Phi_1: Q \ni c \to x(t) \equiv c \in BCL$, then $F': Q \to Q$ and F'(c) = c for every $c \in Q$.

Now, let us put $X, Y = Q, Z = Z_0 = Z_1 = \text{BCL}, \varphi = \varphi_0 = \varphi_1$ and consider the following decomposable map (\breve{D}, \breve{F}) with $\breve{D}: Q \times [0, 1] \xrightarrow{\Phi} \text{BCL} \xrightarrow{\varphi} Q$, where $\breve{\Phi}(c, \lambda) := \{x \in \text{BCL} \mid x(t) = (1 - \lambda)y(t) + \lambda z(t), t \in \mathbb{R}_+, y \in \Phi_0(c), z \in \Phi_1(c)\}.$ It is immediate to see that $\breve{\Phi}$ is an R_{δ} -map. Moreover, one can see that the appropriate diagram is commutative. Hence, (D, F) is homotopic to the identity.

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The Euler characteristic of Q satisfies $\chi(Q) = 1$. Thus, by Corollary 2.2, $Fix(F) \neq \emptyset$ and hence there exists $\tilde{c} \in Q$ such that $\tilde{c} \in F(\tilde{c})$.

On the other hand $F(\tilde{c}) = \tilde{c} - \varepsilon g(\tilde{c})$. Thus $0 \in F(\tilde{c}) - \tilde{c} = -\varepsilon g(\tilde{c})$, and from this $0 \in g(\tilde{c})$.

This ends the proof of Theorem 3.2 and completes the paper.

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