

ALTERNATING HEEGAARD DIAGRAMS AND WILLIAMS SOLENOID ATTRACTORS IN 3-MANIFOLDS

CHAO WANG — YIMU ZHANG

ABSTRACT. We find all Heegaard diagrams with the property “alternating” or “weakly alternating” on a genus two orientable closed surface. Using these diagrams we give infinitely many genus two 3-manifolds, each admits an automorphism whose non-wandering set consists of two Williams solenoids, one attractor and one repeller. These manifolds contain half of Prism manifolds, Poincaré’s homology 3-sphere and many other Seifert manifolds, all integer Dehn surgeries on the figure eight knot, also many connected sums. The result shows that many kinds of 3-manifolds admit a kind of “translation” with certain stability.

1. Introduction

In [7], Smale introduced the solenoid attractor into dynamics as an example of indecomposable hyperbolic non-wandering set. It has a nice geometric model, namely the nested intersections of solid tori. Suppose f is a fibre preserving embedding from a disk fibre bundle N over S^1 into itself, contracting the fibres

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and inducing an expansion on S^1 , then $\bigcap_{i=1}^{\infty} f^i(N)$ is a so-called Smale solenoid. To generalize this kind of construction, in [9], Williams introduced solenoid attractors derived from expansions on 1-dimensional branched manifolds. It also has a geometric model, as the nested intersections of handlebodies.

For a 3-manifold M , many of these attractors can be realized by the geometric models with suitable automorphisms $f \in \text{Diff}(M)$. But in most cases the realization will not be global. Global means that the non-wandering set $\Omega(f)$ is the union of solenoid attractors and repellers. Here a repeller of f is an attractor of f^{-1} . By standard arguments in dynamics, one can show that if $\Omega(f)$ consists of solenoid attractors and repellers, then there must be exactly one attractor and one repeller, and f is like a “translation” on M .

Motivated by the study in Morse theory and Smale’s work in dynamics, the following question was suggested in [3] by Jiang, Ni and Wang who studied this global realization question for Smale solenoids.

QUESTION. When does a 3-manifold admit an automorphism whose non-wandering set consists of solenoid attractors and repellers?

In [3], they showed that for a closed orientable 3-manifold M , there is a diffeomorphism $f: M \rightarrow M$ with the non-wandering set $\Omega(f)$ a union of finitely many Smale solenoids IF and ONLY IF M is a Lens space $L(p, q)$ with $p \neq 0$, namely M has Heegaard genus one and is not $S^1 \times S^2$. They also showed that the diffeomorphism f constructed in the IF part is Ω -stable, but is not structurally stable.

In the opinion of [3], a manifold M admitting a dynamics f such that $\Omega(f)$ consists of one hyperbolic attractor and one hyperbolic repeller presents a symmetry of the manifold with certain stability. The simplest example is the sphere, which admits a dynamics f such that $\Omega(f)$ consists of exactly two hyperbolic fixed points, a sink and a source. Lens spaces give us more such examples when we consider more complicated attractors. It is believed by Jiang, Ni and Wang that many more 3-manifolds admit such symmetries if we replace the Smale solenoids by the Williams solenoids. As a special case, Wang asked whether the Poincaré’s homology 3-sphere admits such a symmetry. What about hyperbolic 3-manifolds?

Similar with the discussion in [3], in [5], Ma and Yu showed that for a closed orientable 3-manifold M , if there is $f \in \text{Diff}(M)$ such that $\Omega(f)$ consists of Williams solenoids, whose defining handlebodies have genus $g \leq 2$, then the Heegaard genus $g(M) \leq 2$. On the other hand, to construct such M and f , they introduced the alternating Heegaard splitting which is a genus two splitting and admits a so-called alternating Heegaard diagram (see Definition 2.5). They showed that if M admits an alternating Heegaard splitting, then there is f such